

Minimizing the makespan of a project with stochastic activity durations under resource constraints

Stefan Creemers
(December, 2014)



IÉSEG
SCHOOL OF MANAGEMENT

KATHOLIEKE UNIVERSITEIT
LEUVEN

Agenda

- Problem setting:
 - Past work
 - The SRCPSP
 - Phase Type (PH) distributions
- Model discussion & comparison
- Results:
 - Solution quality
 - Computational performance
- Contribution

Problem setting



Creemers, Leus, Lambrecht
(2010). Scheduling Markovian
PERT networks to maximize the
net present value, Operations
Research Letters, 38, pp. 51-56.

Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, Operations Research Letters, 38, pp. 51-56.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy

Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, Operations Research Letters, 38, pp. 51-56.



Creemers (under review) Minimizing the makespan of a project with stochastic activity durations under resource constraints, Journal of Scheduling.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy

Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, *Operations Research Letters*, 38, pp. 51-56.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy



Creemers (under review) Minimizing the makespan of a project with stochastic activity durations under resource constraints, *Journal of Scheduling*.

1. Minimum-makespan objective
2. Renewable resources
3. General activity durations (PH approximation)
4. Use of an improved/modified SDP recursion

Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, Operations Research Letters, 38, pp. 51-56.



Creemers (under review) Minimizing the makespan of a project with stochastic activity durations under resource constraints, Journal of Scheduling.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy

1. Minimum-makespan objective
2. Renewable resources
3. General activity durations (PH approximation)
4. **Use of an improved/modified SDP recursion**

Improvement of the SDP recursion

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
10	0.8	100%	0.00	0.00	-
10	0.6	100%	0.00	0.00	-
10	0.4	100%	0.00	0.00	6.81
20	0.8	100%	0.00	0.00	-
20	0.6	100%	0.01	0.00	27.25
20	0.4	100%	0.46	0.03	17.60
30	0.8	100%	0.01	0.00	17.53
30	0.6	100%	0.33	0.02	14.90
30	0.4	100%	26.92	1.49	18.12
40	0.8	100%	0.03	0.00	12.41
40	0.6	100%	6.62	0.49	13.62
40	0.4	97%	2,337.96	72.25	32.36
50	0.8	100%	0.15	0.01	10.60
50	0.6	100%	100.28	4.43	22.62
50	0.4	13%	52,267.30	823.71	63.45
60	0.8	100%	0.74	0.06	12.36
60	0.6	100%	2,210.08	67.87	32.56
60	0.4	0%	-	-	-

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
70	0.8	100%	3.19	0.24	13.09
70	0.6	73%	17,495.49	378.64	46.21
70	0.4	0%	-	-	-
80	0.8	100%	10.81	0.79	13.65
80	0.6	30%	72,473.41	1,188.01	61.00
80	0.4	0%	-	-	-
90	0.8	100%	50.64	3.15	16.06
90	0.6	0%	-	-	-
90	0.4	0%	-	-	-
100	0.8	100%	171.42	9.60	17.85
100	0.6	0%	-	-	-
100	0.4	0%	-	-	-
110	0.8	100%	1,193.88	40.93	29.17
110	0.6	0%	-	-	-
110	0.4	0%	-	-	-
120	0.8	100%	12,789.06	260.66	49.06
120	0.6	0%	-	-	-
120	0.4	0%	-	-	-

Improvement of the SDP recursion

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
10	0.8	100%	0.00	0.00	-
10	0.6	100%	0.00	0.00	-
10	0.4	100%	0.00	0.00	6.81
20	0.8	100%	0.00	0.00	-
20	0.6	100%	0.00	0.00	-
20	0.4	100%	0.00	0.00	-
30	0.8	100%	0.00	0.00	-
30	0.6	100%	0.00	0.00	-
30	0.4	100%	0.00	0.00	-
40	0.8	100%	0.00	0.00	-
40	0.6	100%	0.00	0.00	-
40	0.4	100%	0.00	0.00	-
50	0.8	100%	0.00	0.00	-
50	0.6	100%	100.28	4.43	22.62
50	0.4	13%	52,267.30	823.71	63.45
60	0.8	100%	0.74	0.06	12.36
60	0.6	100%	2,210.08	67.87	32.56
60	0.4	0%	-	-	-

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
70	0.8	100%	3.19	0.24	13.09
70	0.6	73%	17,495.49	378.64	46.21
70	0.4	0%	-	-	-
80	0.8	100%	0.00	0.00	-
80	0.6	100%	0.00	0.00	-
80	0.4	100%	0.00	0.00	-
90	0.8	100%	0.00	0.00	-
90	0.6	100%	0.00	0.00	-
90	0.4	100%	0.00	0.00	-
100	0.8	100%	0.00	0.00	-
100	0.6	100%	0.00	0.00	-
100	0.4	100%	0.00	0.00	-
110	0.8	100%	0.00	0.00	-
110	0.6	0%	-	-	-
110	0.4	0%	-	-	-
120	0.8	100%	12,789.06	260.66	49.06
120	0.6	0%	-	-	-
120	0.4	0%	-	-	-

In comparison with the model of Creemers et al. (2010), the computation speed has been increased by factor 56 (= 56 times faster).

Improvement of the SDP recursion

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
10	0.8	100%	0.00	0.00	-
10	0.6	100%	0.00	0.00	-
10	0.4	100%	0.00	0.00	6.81
20	0.8	100%	0.00	0.00	-
20	0.6	100%	0.00	0.00	-
20	0.4	100%	0.00	0.00	-
30	0.8	100%	0.00	0.00	-
30	0.6	100%	0.00	0.00	-
30	0.4	100%	0.00	0.00	-
40	0.8	100%	0.00	0.00	-
40	0.6	100%	0.00	0.00	-
40	0.4	100%	0.00	0.00	-
50	0.8	100%	0.00	0.00	-
50	0.6	100%	100.28	4.43	22.62
50	0.4	13%	52,267.30	823.71	63.45
60	0.8	100%	0.74	0.06	12.36
60	0.6	100%	2,210.08	67.87	32.56
60	0.4	0%	-	-	-

n	OS	% Solved	Average CPU (2010)	Average CPU (improved)	Average Factor
70	0.8	100%	3.19	0.24	13.09
70	0.6	73%	17,495.49	378.64	46.21
70	0.4	0%	-	-	-
80	0.8	100%	0.00	0.00	-
80	0.6	100%	0.00	0.00	-
80	0.4	100%	0.00	0.00	-
90	0.8	100%	0.00	0.00	-
90	0.6	100%	0.00	0.00	-
90	0.4	100%	0.00	0.00	-
100	0.8	100%	0.00	0.00	-
100	0.6	100%	0.00	0.00	-
100	0.4	100%	0.00	0.00	-
110	0.6	0%	-	-	-
110	0.4	0%	-	-	-
120	0.8	100%	12,789.06	260.66	49.06
120	0.6	0%	-	-	-
120	0.4	0%	-	-	-

In comparison with the model of Creemers et al. (2010), the computation speed has been increased by factor 56 (= 56 times faster).

When compared to the model of Sobel et al. (2009), the new model is even **840 times faster**.

Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, Operations Research Letters, 38, pp. 51-56.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy



Creemers (under review) Minimizing the makespan of a project with stochastic activity durations under resource constraints, Journal of Scheduling.

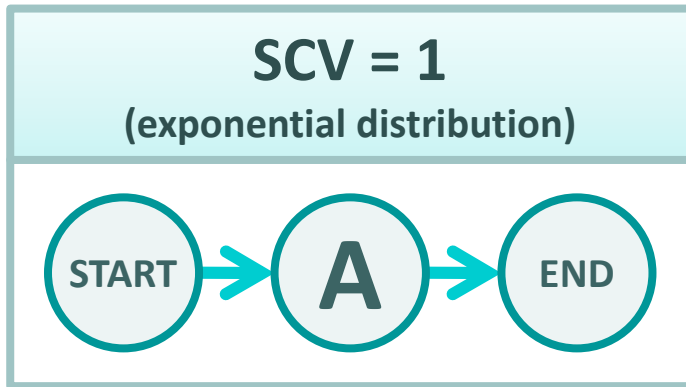
1. Minimum-makespan objective
2. Renewable resources
3. **General activity durations (PH approximation)**
4. Use of an improved/modified SDP recursion

Model extensions: PH distributions

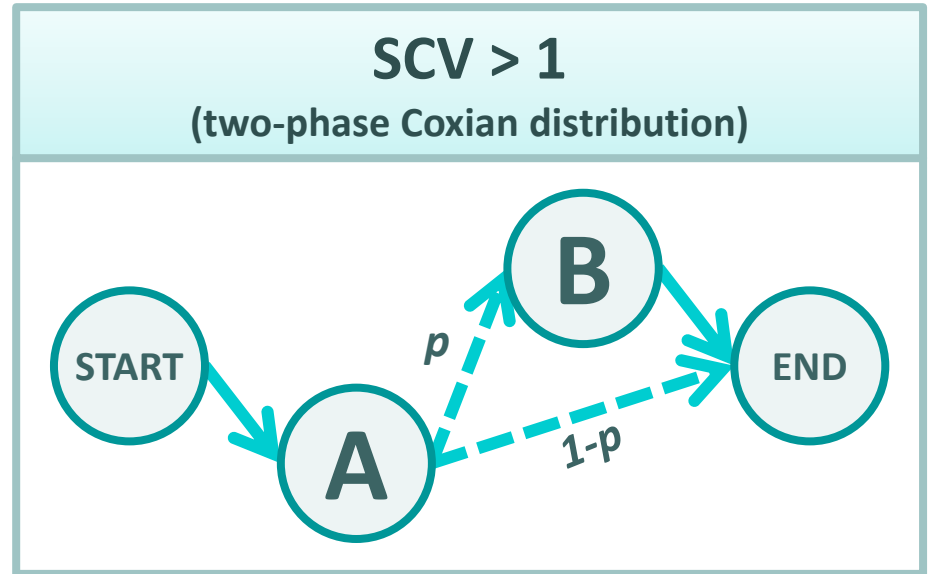
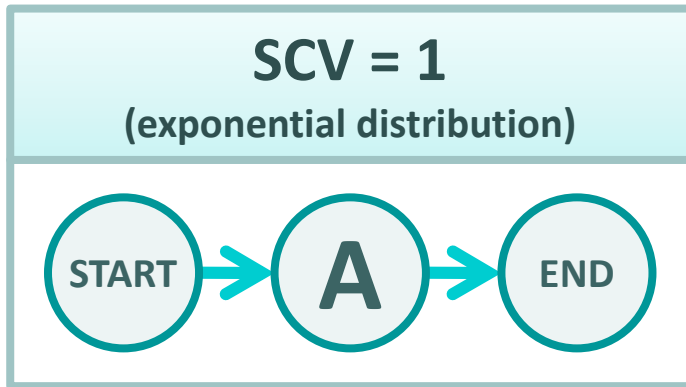
- Introduced by Neuts in 1981
- A Phase Type (PH) distribution is a mixture of exponential distributions
- The exponential, Erlang, Coxian, and hyper-exponential distribution are all examples of a PH distribution
- We use simple PH distributions to match the first two moments of the distribution of the activity duration (more advanced PH distributions, however, can also be used)

PH distributions: Example of a single activity

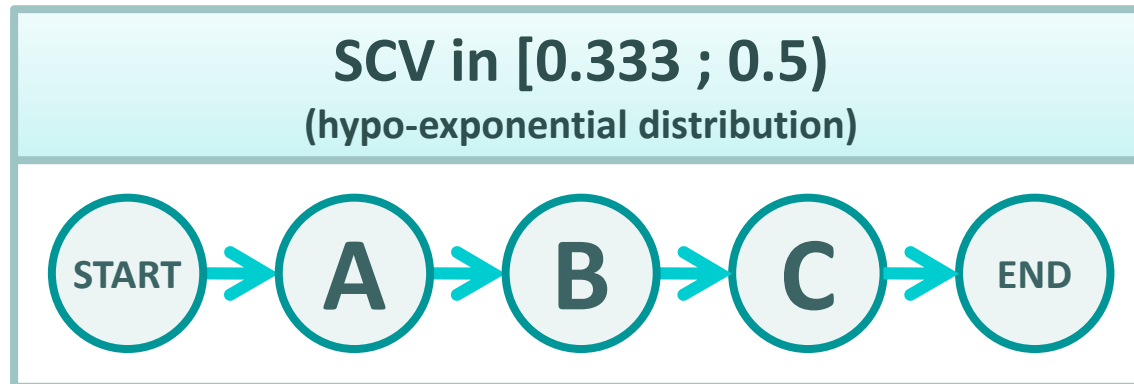
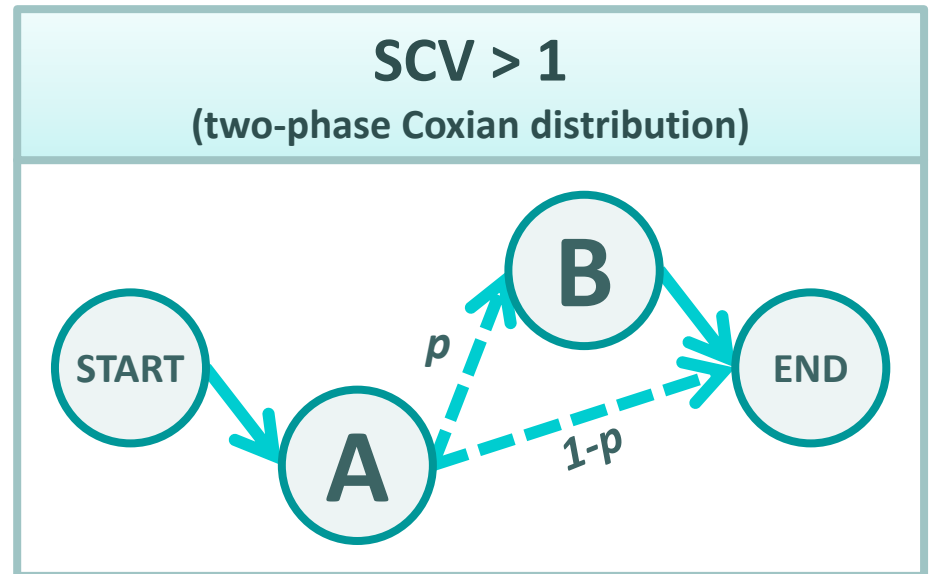
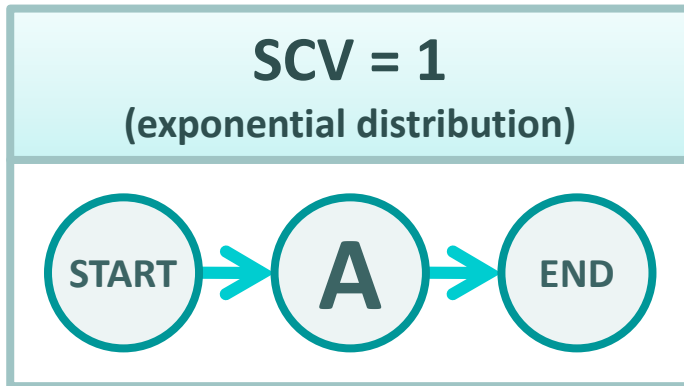
PH distributions: Example of a single activity



PH distributions: Example of a single activity

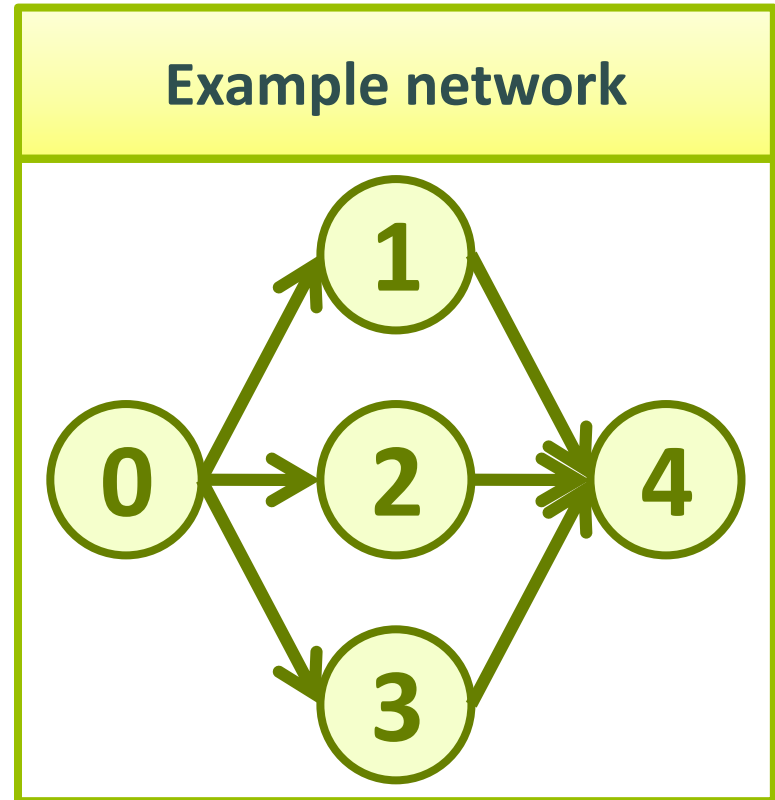


PH distributions: Example of a single activity



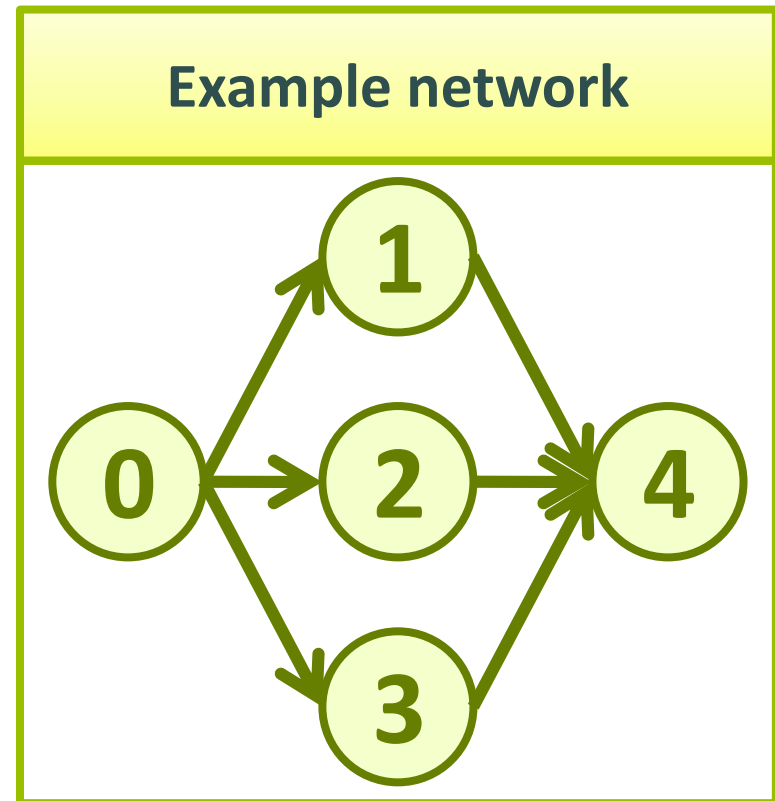
PH distributions: Example of a project network

PH distributions: Example of a project network

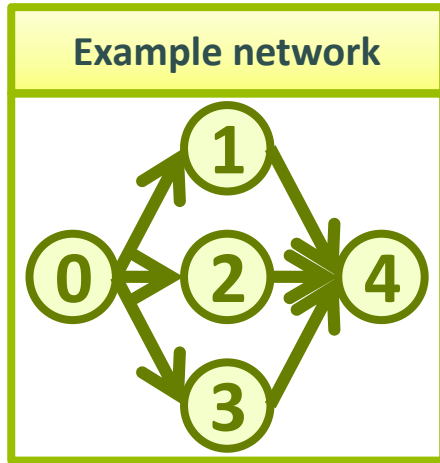


PH distributions: Example of a project network

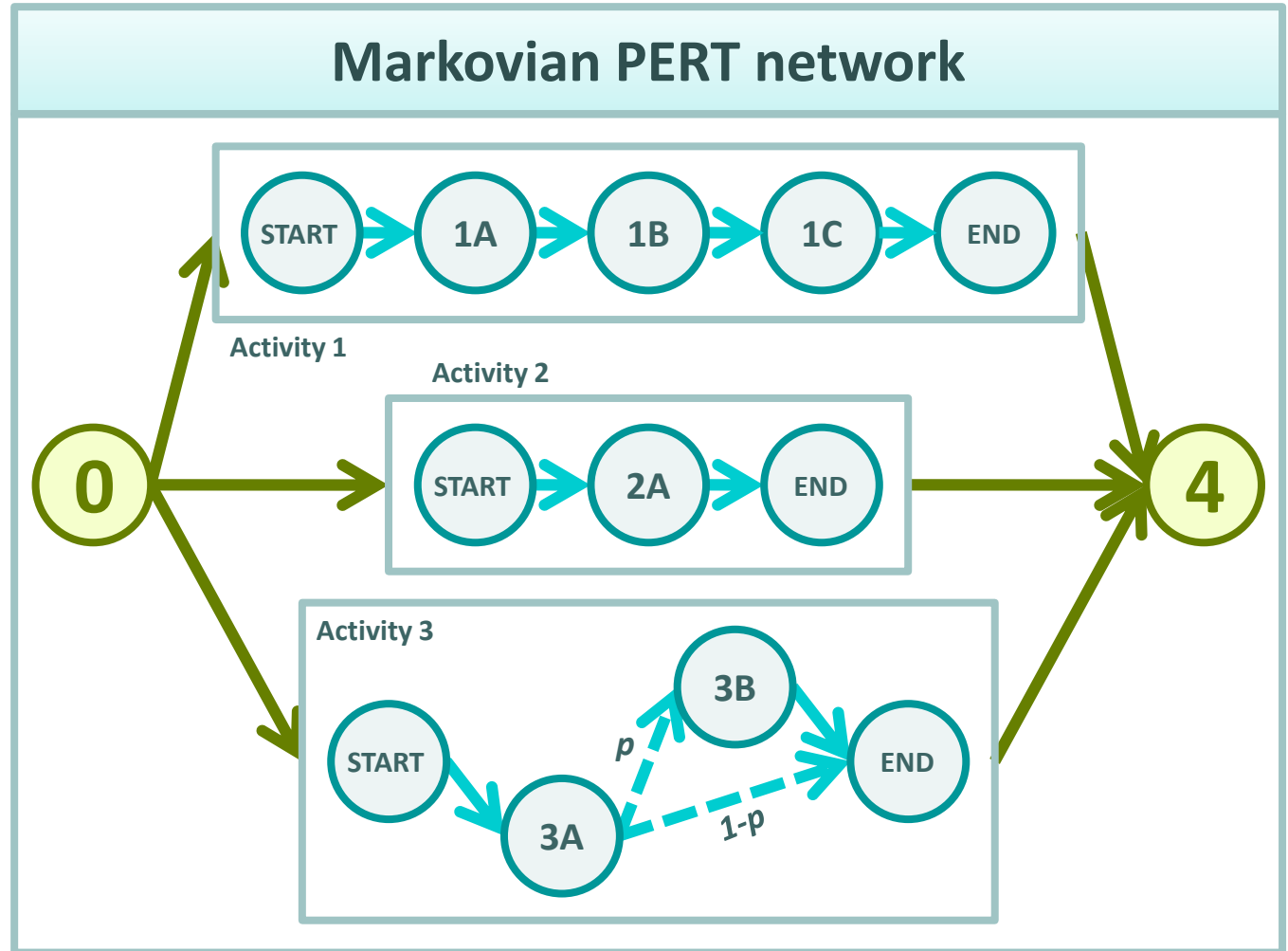
Activity	SCV
0	Dummy start
1	SCV in $[0.33;0.5)$
2	SCV = 1
3	SCV > 1
4	Dummy finish



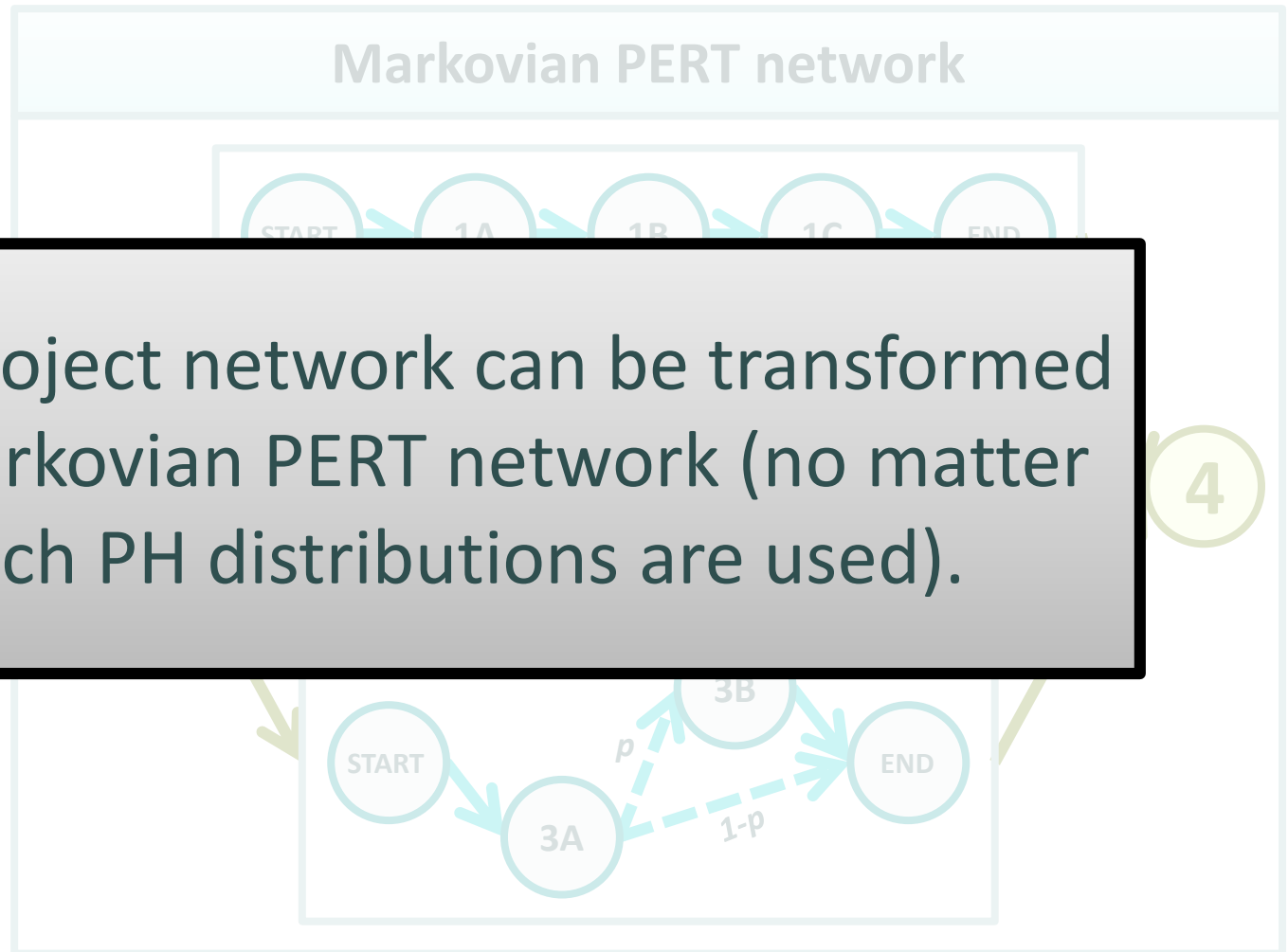
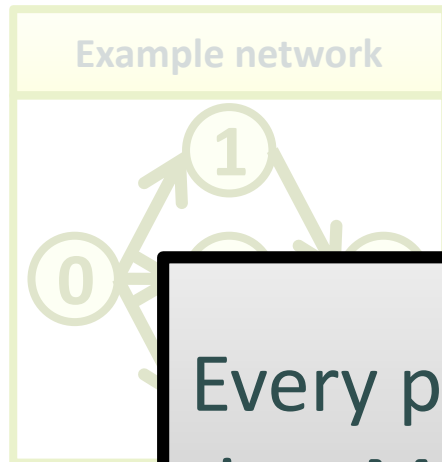
PH distributions: Example of a project network



Activity	SCV
0	Dummy start
1	SCV in $[0.33; 0.5)$
2	SCV = 1
3	SCV > 1
4	Dummy finish



PH distributions: Example of a project network



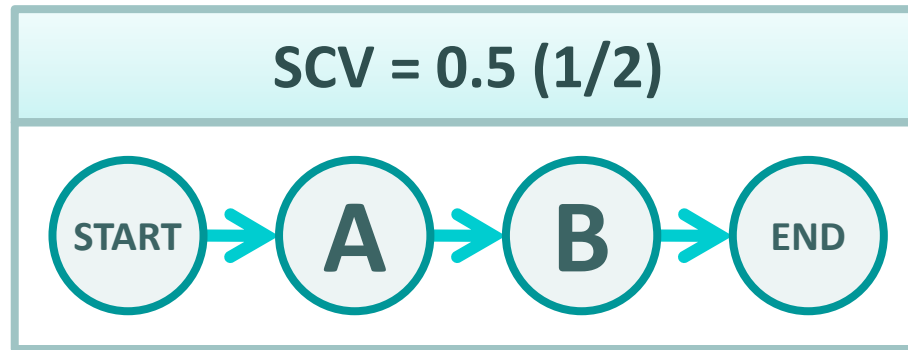
Every project network can be transformed in a Markovian PERT network (no matter which PH distributions are used).

Activity	
0	
1	SCV in $[0.33; 0.5)$
2	SCV = 1
3	SCV > 1
4	Dummy finish

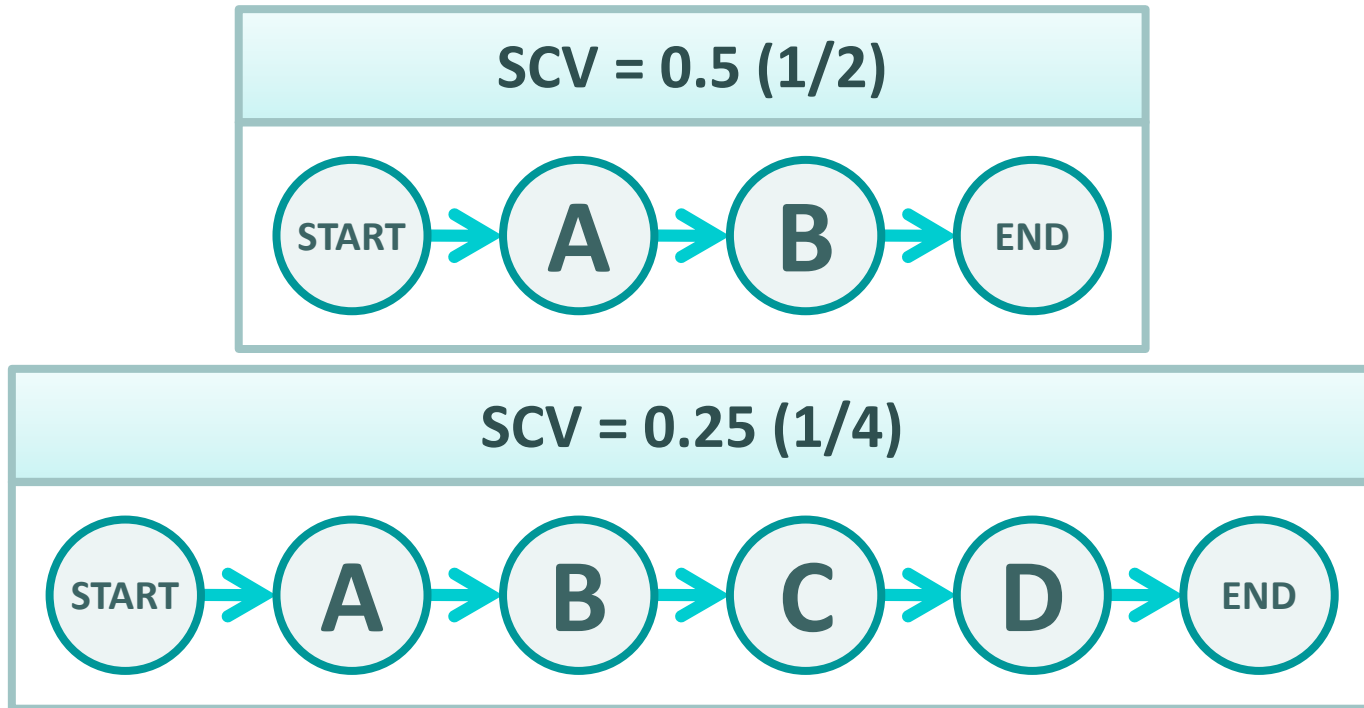
4

PH distributions: What about low variability?

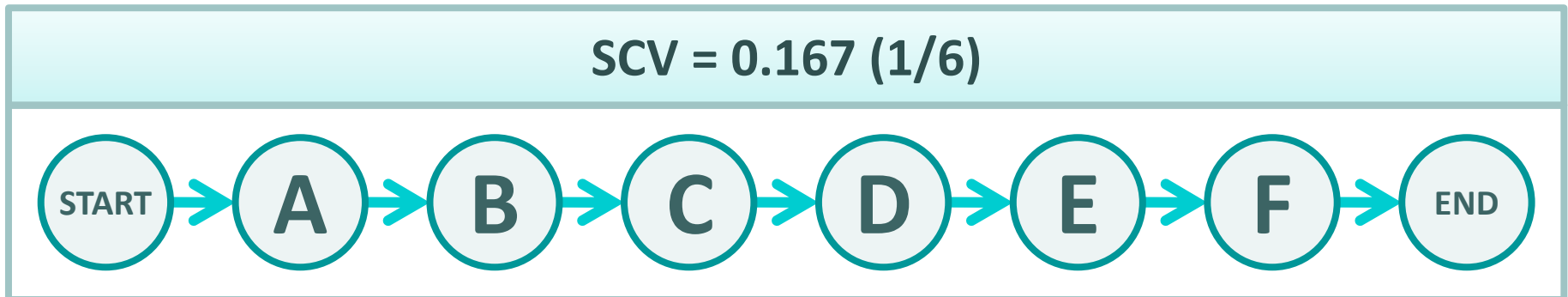
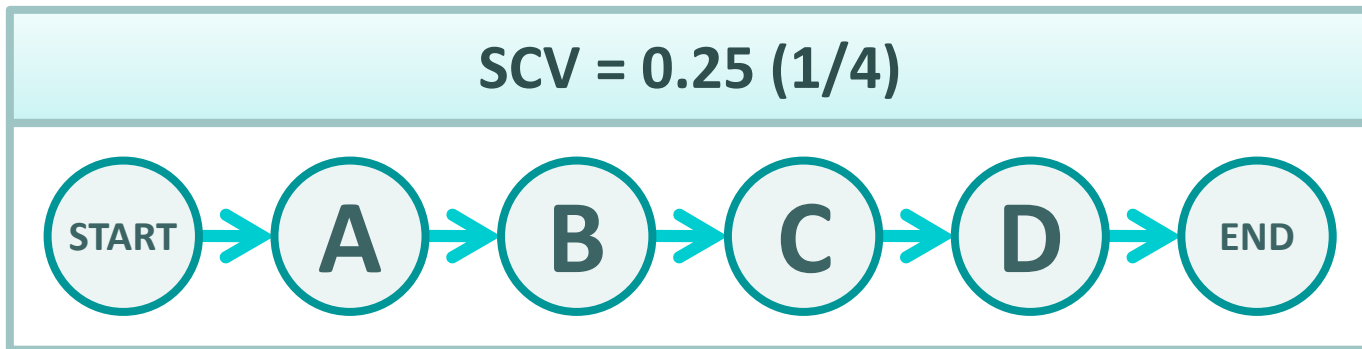
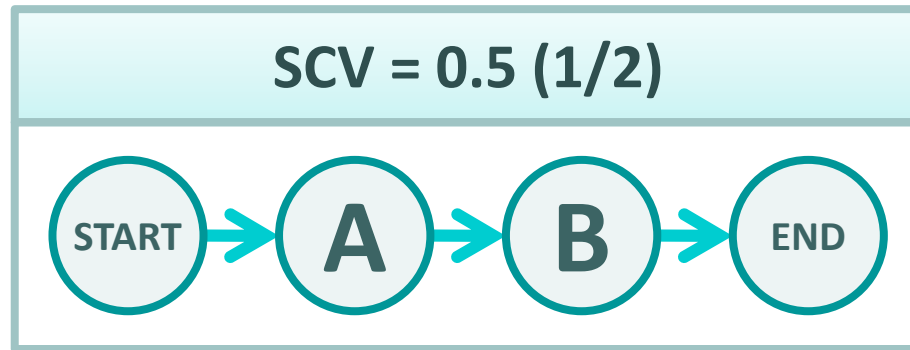
PH distributions: What about low variability?



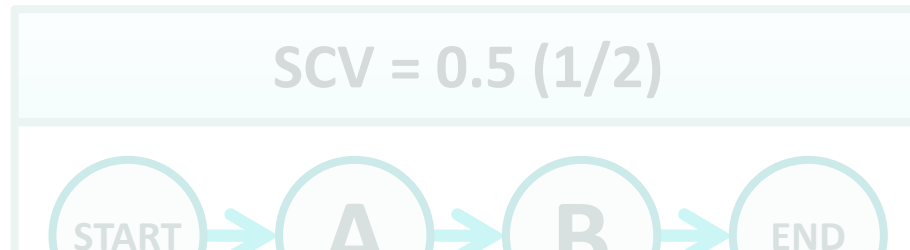
PH distributions: What about low variability?



PH distributions: What about low variability?



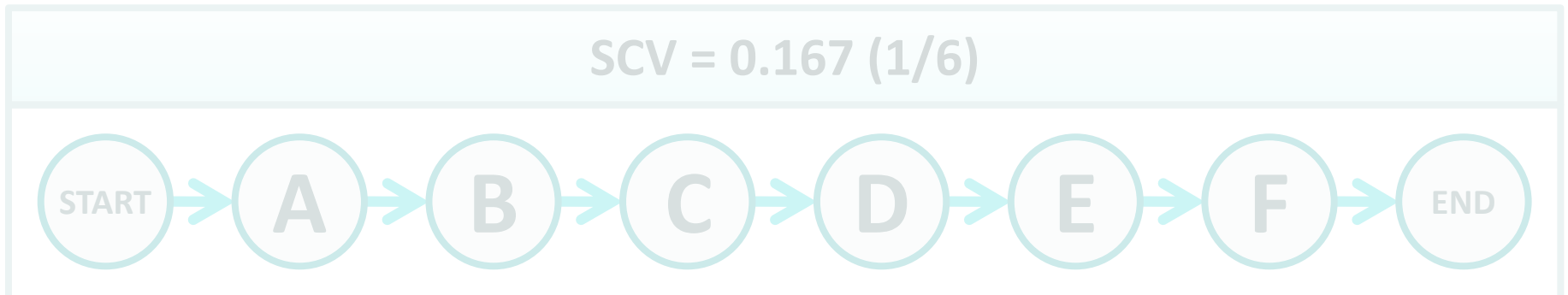
PH distributions: What about low variability?



Low variability duration variability inflates the size of the Markovian PERT network.

=>

Our model works best when duration variability is moderate to high.



Problem setting



Creemers, Leus, Lambrecht (2010). Scheduling Markovian PERT networks to maximize the net present value, Operations Research Letters, 38, pp. 51-56.

1. Maximum-eNPV objective
2. No resources
3. Exponentially-distributed activity durations
4. Use of a SDP recursion to obtain the optimal policy



Creemers (under review) Minimizing the makespan of a project with stochastic activity durations under resource constraints, Journal of Scheduling.

1. **Minimum-makespan objective**
2. **Renewable resources**
3. General activity durations (PH approximation)
4. Use of an improved/modified SDP recursion

Literature on the SRCPSP

Literature on the SRCPSP

Author	Tsai and Gemmill (1998)
Date	1998
Method	Simulated annealing & tabu search
Policy class	RB (Resource-Based)

Literature on the SRCPSP

Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)
Date	1998	2009
Method	Simulated annealing & tabu search	Genetic algorithm
Policy class	RB (Resource-Based)	AB (Activity-Based)

Literature on the SRCPSP

Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)
Date	1998	2009	2011
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local- search procedure
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)

Literature on the SRCPSP

Heuristic approaches			
Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)
Date	1998	2009	2011
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local- search procedure
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)

Literature on the SRCPSP

Heuristic approaches				
Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)
Date	1998	2009	2011	2001
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local- search procedure	Five B&B algorithms
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES

Literature on the SRCPSP

Heuristic approaches					
Author	Tsai and Gemmill (1998)	Ballestin & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local- search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestin & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestin & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestin & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					
J30 (PSPLIB)					
J60 (PSPLIB)					
J120 (PSPLIB)					
Patterson					
Golenko					

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					
J30 (PSPLIB)					
J60 (PSPLIB)					
J120 (PSPLIB)					
Patterson					
Golenko					

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					
J30 (PSPLIB)					
J60 (PSPLIB)					
J120 (PSPLIB)					
Patterson					
Golenko					

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestìn & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					
J30 (PSPLIB)					
J60 (PSPLIB)					
J120 (PSPLIB)					IMPOSSIBLE
Patterson					
Golenko					

Literature on the SRCPSP

	Heuristic approaches			Optimal approaches	
Author	Tsai and Gemmill (1998)	Ballestin & Leus (2009)	Ashtiani et al. (2011)	Stork (2001)	Creemers (201?)
Date	1998	2009	2011	2001	Under review
Method	Simulated annealing & tabu search	Genetic algorithm	Two-phase local-search procedure	Five B&B algorithms	SDP recursion
Policy class	RB (Resource-Based)	AB (Activity-Based)	PP (PreProcessor)	AB & ES	Elementary policies
Data set					
J30 (PSPLIB)					
J60 (PSPLIB)					
J120 (PSPLIB)					IMPOSSIBLE
Patterson					
Golenko					SCV = 0.014

Results: Solution quality

Results: Solution quality

- We optimize over a more general class of policies => we expect better results.
- From Ballestìn & Leus (2009) we obtained the results for the J30 & J60 problem instances if activity durations are exponentially distributed:
 - J30 average improvement of solution quality of 9,11%
 - J60 average improvement of solution quality of 15,9%

⇒ Significant improvement of solution quality!

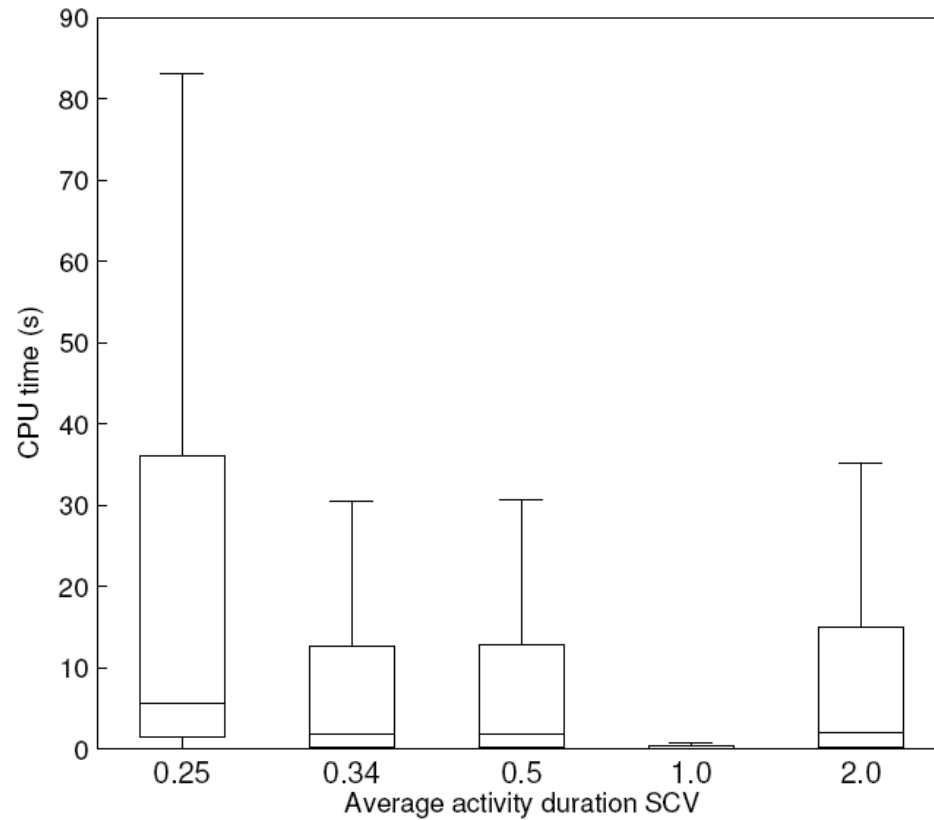
⇒ Optimality gap of heuristic approaches increases with network size

Results: Solution quality

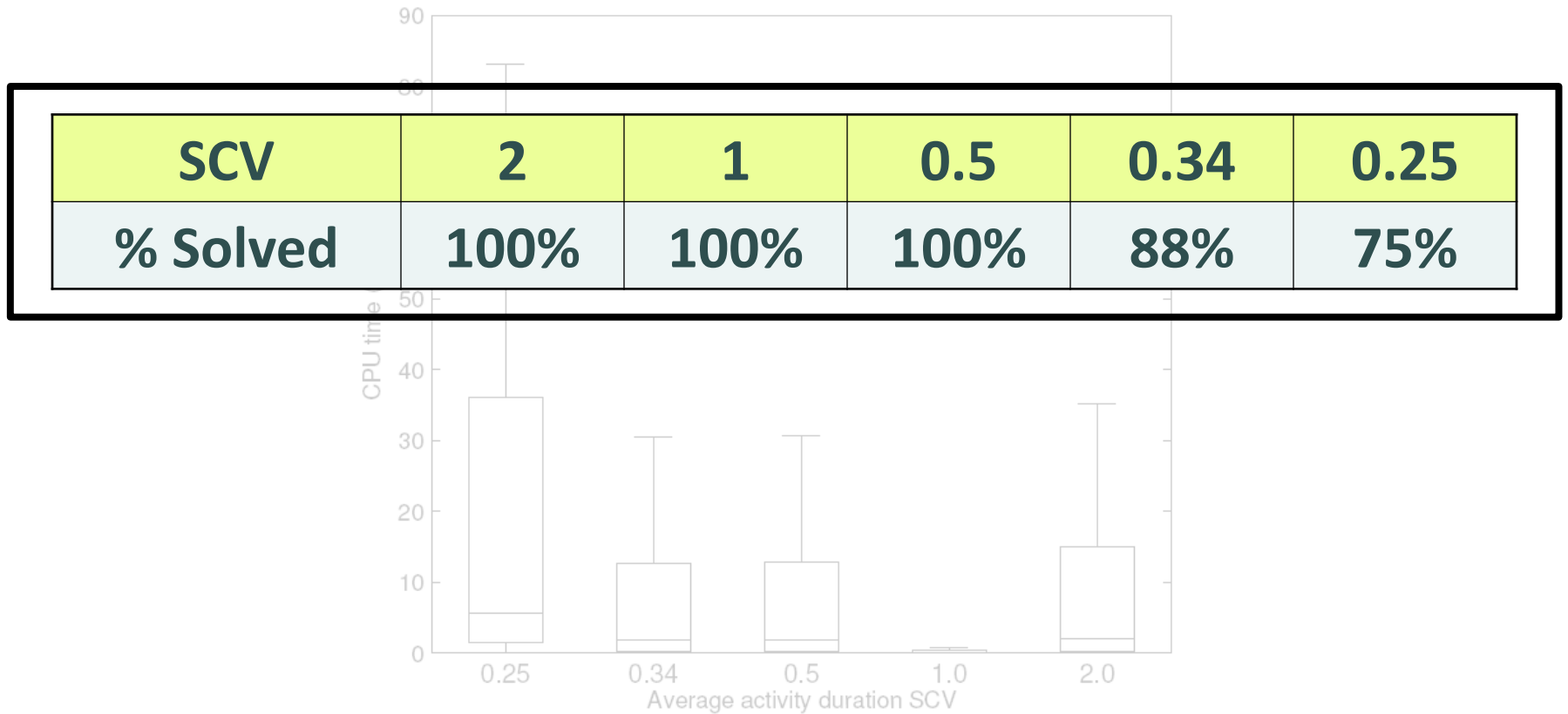
- We optimize over a more general class of policies
=> we expect better results.
 - From Ballestìn & Leus (2009) we obtained the results for the J30 & J60 problem instances if activity durations are exponentially distributed:
 - J30 average improvement of solution quality of 9,11%
 - J60 average improvement of solution quality of 15,9%
- ⇒ Significant improvement of solution quality!
- ⇒ Optimality gap of heuristic approaches increases with network size

Results: Computational performance

Results: Computational performance (J30 - PSPLIB)

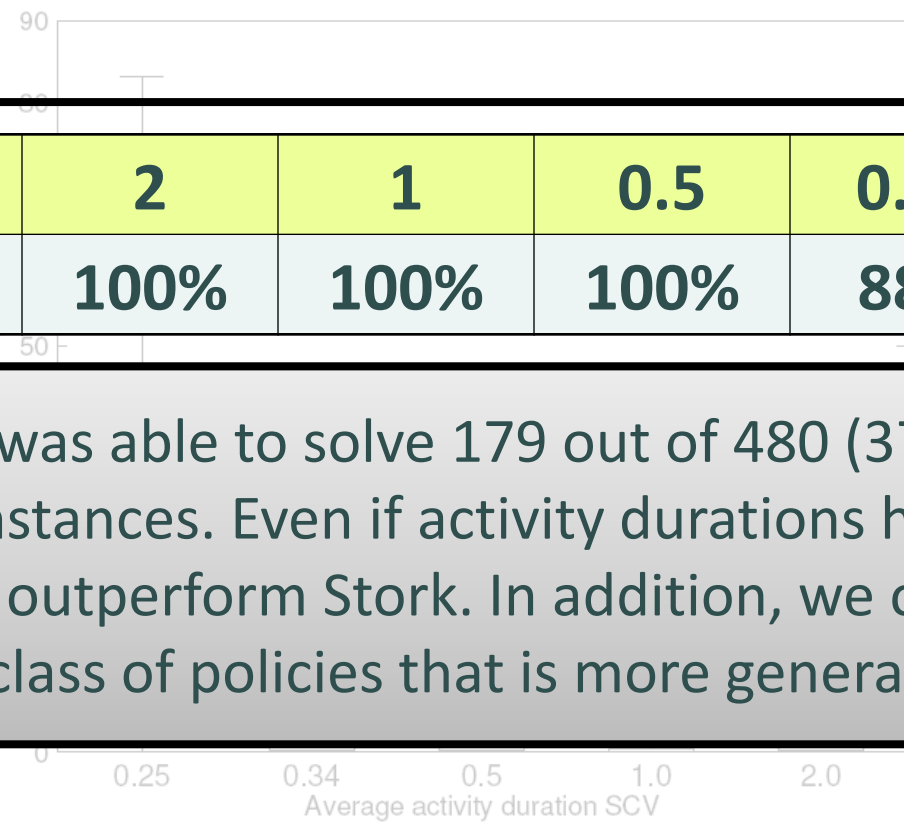


Results: Computational performance (J30 - PSPLIB)



SCV	2	1	0.5	0.34	0.25
% Solved	100%	100%	100%	88%	75%

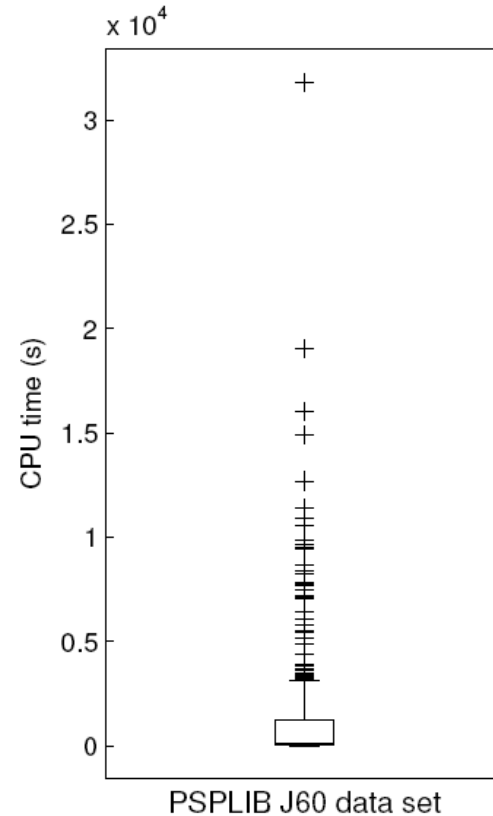
Results: Computational performance (J30 - PSPLIB)



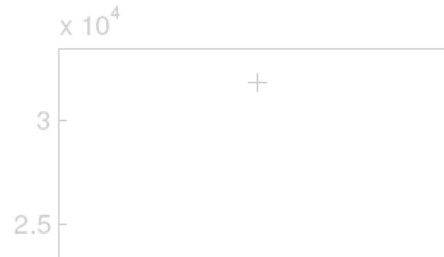
SCV	2	1	0.5	0.34	0.25
% Solved	100%	100%	100%	88%	75%

Stork (2001) was able to solve 179 out of 480 (37%) of the J30 problem instances. Even if activity durations have limited variability, we outperform Stork. In addition, we optimize over a class of policies that is more general!

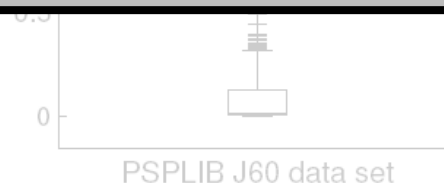
Results: Computational performance (J60 - PSPLIB)



Results: Computational performance (J60 - PSPLIB)



Stork (2001) was able to solve 11 out of 480 (2%) of the J60 problem instances. We solve 301 instances (63%) if activity durations are exponentially distributed.



Contributions

Contributions



We improve the SDP recursion of Creemers et al. (2010) and increase computation speed by a factor of 56.

Contributions



We improve the SDP recursion of Creemers et al. (2010) and increase computation speed by a factor of 56.



We extend the model of Creemers et al. (2010) in order to solve the SRCPSP. We add resource constraints, general activity durations, and use a minimum-makespan objective.

Contributions



We improve the SDP recursion of Creemers et al. (2010) and increase computation speed by a factor of 56.



We extend the model of Creemers et al. (2010) in order to solve the SRCPSP. We add resource constraints, general activity durations, and use a minimum-makespan objective.



Solving the SRCPSP makes sense if activities have moderate- to high levels of duration variability. For this setting, our model outperforms the state-of-the-art (both in solution quality & in computation speed).

